

OPERATING INSTRUCTIONS

Single Channel Hall Effect Speed Sensor

DSF 1810.07 PxHV



Product ID

| | Type # | Product # | Drawing # | | | |
|---------------------------|---|---|-----------------------------|--|--|--|
| | DSF 1810.07 PHV | 374Z-05540 | 114494 | | | |
| | DSF 1810.07 P2HV | 3742613785 | 114494 | | | |
| General | | | | | | |
| Function | The speed sensors DSF are suitable, in conjunction with a pole wheel, for generating square wave signals proportional to rotary speeds. They have a static behaviour, so that the pulse generation is guaranteed down to a speed corresponding to a frequency of 0Hz. The sensor features a time out function over 50ms to avoid erroneous pulses induced by torsion of the camshaft. This characteristic leads to the sensor specific frequency range of 0Hz to 16Hz. The sensor function is independent of the rotational orientation of the sensor axis. | | | | | |
| Certification | The DSF sensors are cer | The DSF sensors are certified by Germanischer Lloyd (GL): | | | | |
| Certificate n° 17332-00HH | | | | | | |
| Technical data | | | | | | |
| Supply voltage | 835 VDC, maximum a | lowed ripple voltage 2 | 5 mVpp | | | |
| | The sensor is protected | l against reverse pol | arity of the supply voltage | | | |
| Current consumption | max. 25mA (without load) | | | | | |
| Signal output | Square wave signal on a push-pull output stage, DC coupled to the power supply Reference potential is the negative input of the power supply Maximum load current I_{max} = 40 mA, sink/source Pulse width = 250 μs, independent of the frequency measured Output voltage U_{high} > U_{supply}-4.0V at I_{max} Output voltage U_{low} < 2.0V at I_{max} | | | | | |
| Frequency range | 0 Hz16 Hz | | | | | |

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| Electromagnetic | Complies with 2004/108 | FC | | | |
|-----------------------------|---|---|---------------------------------------|-------------------|--|
| compatibility (EMC): | Compiles with 2004/100 EC | | | | |
| | Immunity with the cable shield connected to 0V: | | | | |
| | Electrostatic discharge up to ±4kV | e to the s | ensor housing, cable | shield and cable: | |
| | according to IEC/EN 61000-4-2 Radiated electromagnetic field: up to 30V/m, 80% AM, 1kHz in the range of 1MHz to 1000MHz according to IEC/EN61000-4-3 Fast transients (HF-Burst), capacitively coupled to the sensor cable: up to ±4kV according to IEC/EN 61000-4-4 | | | | |
| | | | | | |
| | | | | | |
| | | | | | |
| | | | | | |
| | | | | | |
| Housing | sing Stainless steel 1.4305, front side sealed hermetically and resistant again splashing water, oil, conducting carbon- or ferrous dust and salt mist. Ele | | | | |
| | | | | | |
| | Dimensions according to | drawing | | | |
| | Maximum fastening torg | ue: 50 N r | a with M18v1 | | |
| | | ue. Ju ini | | | |
| Cable | Type # | | Cable | Cable length | |
| | -) | | [Jaquet part #] | [mm] | |
| | DSF 1810.07 PHV | | 824L-36499 | 1800 | |
| | DSF 1810.07 P2HV 824L-36499 2100 | | | | |
| | Jaquet cable type | Properties | | | |
| | | PTFE_cable, 3-wire, 0.75 mm ² (~AWG 18), outer-Ø | | | |
| | max. 5.5 mm, bending radius min. 90 mm, | | | | |
| | 824L-36499 Operating temperature: -90°C to +260°C | | | C to +260°C | |
| | | | | | |
| Connector | — <i>•</i> | | | - | |
| | | Connector [Jaquet part no.] | | | |
| | DSF 1810.07 P2HV | 820E-3 | 57112 | | |
| | | | | | |
| | Jaquet connector | Manufacturer code | | | |
| | 820E-37112 | ITT-Ca | ITT-Cannon CA08COM-E14S-2P-B-44-E0-CS | | |
| | | | | | |
| Requirements for pole wheel | Toothed wheel of a magnetically permeable material (e.g. Steel 1.0036) | | | | |
| | • Involute gear medule > 1 | | | | |
| | • Tooth width > $6mm$ | | | | |
| | Side offset < 0.2mm | | | | |
| | Eccentricity < 0.2mm | | | | |
| | Airgap | Modul | 1: 0,11,5 m | ım | |
| | | Modul | 2: 0,12,0 m | IM | |
| | - | ≥ Modul | 4: 0,12.0 m | IM | |
| Isolation | Housing, cable shield and electronics are galvanically separated | | | | |
| | (500V / 50HZ / 1 min) | | | | |
| | | | | | |
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OPERATING INSTRUCTIONS

| Protection class | IP68 (head) and IP67 (connector, cable outlet) | | | |
|-----------------------|--|--|--|--|
| Vibration immunity | 5g in the range of 5Hz 2000Hz | | | |
| Operating temperature | Sensor head: -40°C +125°C Cable: according to cable specifications (see above) Connector: according to connector specification | | | |
| Further Information | | | | |
| Safety | All mechanical installations must be carried out by an expert. General safety requirements have to be met. | | | |
| Connection | The sensors must be connected according to the sensor drawing. Sensor wires are susceptible to radiated noise. Therefore, the following points have to be considered when connecting a sensor: The sensor wires must be positioned as far as possible from large electrical machines. The applied cable has to be a shielded three-conductor cable. Its shield has to be connected to the designated terminal They must not run close to power cables. The sensor cable should be placed as far as possible from large electrical machinery It is advantageous to keep the distance between sensor and instrument as short as possible. If the signal and standards requirements are met, the sensor cable may be lengthened via a terminal box located in an IP20 connection area in accordance with EN 60529. As an extension cable we are recommending the JAQUET cable Art. No. 824L-31081 | | | |
| Installation | The sensor has to be aligned to the center of the pole wheel according to the sensor drawing. A deviation in positioning may affect the performance and decrease the noise immunity of the sensor. Within the air gap specified the amplitude of the output signals is not influenced by the air gap. The smallest possible pole wheel to sensor gap should be set, however, the gap should be set in a way to prevent the front face of the sensor from touching the pole wheel. The sensor should be positioned such that the center of the sensor face corresponds to the middle of a pole wheel tooth. For larger teeth a misalignment of the sensor must be at a minimum of 3 mm from either edge of the pole wheel under all operating conditions. A solid and vibration free mounting of the sensor is important. Sensor vibration relative to the pole wheel may add spurious noise to the signal or additional pulses. The sensors are insensitive to oil, grease etc. and can be installed in arduous conditions. | | | |
| Operation | The sensor is designed for normal use in its dedicated environment. The manufacturer cannot take responsibility for any abnormal use that might lead to a reduced lifetime of the sensor. | | | |
| Maintenance | The product cannot be repaired. | | | |
| Transport | The product must be handled with care to prevent damage of the front face. | | | |
| Storage | Product must be stored in dry conditions. The storage temperature corresponds to the operation temperature. | | | |
| Disposal | Product must be disposed of properly, it must not be disposed as domestic waste. | | | |

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